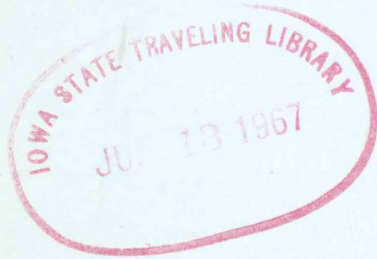


TA
7
.I83
no.56
1967

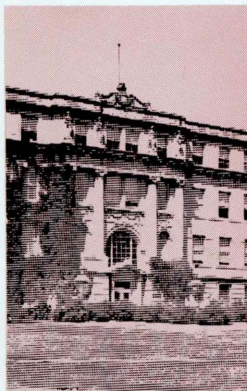
REPORT

56



EFFECT OF ROTATION ON THE GROWTH OF ALFVEN WAVE

by G. A. Nariboli



ENGINEERING RESEARCH INSTITUTE

IOWA STATE UNIVERSITY • AMES, IOWA

**ENGINEERING
RESEARCH
ENGINEERING
RESEARCH
ENGINEERING
RESEARCH
ENGINEERING
RESEARCH
ENGINEERING
RESEARCH
ENGINEERING
RESEARCH**

**REPORT
56**

**EFFECT OF ROTATION
ON THE GROWTH OF ALFVEN WAVE**

by Dr. G. A. Nariboli,

Price: \$2.00

Associate Professor,
Department of Engineering Mechanics

April, 1967

**ENGINEERING RESEARCH INSTITUTE
IOWA STATE UNIVERSITY AMES**

STATE LIBRARY OF IOWA
17 I64ERI 9:56 1967 sdoc
Nariboli, G. A./Effect of rotation on th



3 1723 00025 0068

College of Engineering

George R. Town
Dean

David R. Boylan
Director, Engineering Research Institute

Burton J. Gleason
Head, Engineering Publications Office
Administrative Assistant to the Dean

Tom C. Cooper
Editor, Engineering Research Institute

Iowa State University,
104 Marston Hall,
Ames, Iowa 50010

EFFECT OF ROTATION ON THE GROWTH OF ALFVEN WAVE

by

G. A. Nariboli

1. Summary: The presence of rotation leads to a nonvanishing rate of growth of the discontinuity across an Alfvén wave front. The two integrals obtained and the transversality completely determine the discontinuity.

2. Introduction and Basic Equations: In M.H.D., the discontinuity across an Alfvén wave front does not grow; specifically its time rate of growth vanishes. We discuss here the effect of rotation on this discontinuity.

The linearised problem is studied by the use of the Fourier transform technique⁽¹⁾. We use the theory of Singular surfaces⁽²⁾ and the Ray Theory⁽³⁾. We study without linearising and taking the state ahead of the front arbitrary, but steady.

Cartesian tensor notation is used, with (x_i) denoting coordinates. The wave front $\Sigma(t)$ moves with a speed (G) normal to itself. The unit normal to the surface is denoted by (n_i) . A Gaussian system (u^α) ($\alpha = 1, 2$) is used to describe $\Sigma(t)$ and $(x_{i,\alpha'})$ denote partial derivatives of (x_i) with respect to (u^α) . The first and the second fundamental forms of the surface are denoted by $(g_{\alpha\beta})$ and $(b_{\alpha\beta})$. If $f(x_i, t) = 0$ is the equation of the wave front, we denote the gradient vector by $(p_i = f_{,i} = pn_i)$. We can then show that^(3,4,5)

$$Gp - 1 = 0$$

(1.1)

Assuming (G) depends on (x_i) and (n_i) , we can write the Ray equations as^(3,4,5)

$$\begin{aligned} v_i &\equiv \frac{dx_i}{dt} = \frac{\partial(Gp)}{\partial p_i} \\ &= G n_i + (\delta_{ij} - n_i n_j) \frac{\partial G}{\partial n_j}, \end{aligned} \quad (1.2)$$

$$\frac{dp_i}{dt} = -p \frac{\partial G}{\partial x_i}. \quad (1.3)$$

From (1.2), we have

$$v_\alpha = x_{i,\alpha} \frac{\partial G}{\partial n_i}. \quad (1.4)$$

Let (d/dt) denote the derivative along the rays and $(\delta/\delta t)$, that following the normal trajectories. We then have^(4,5)

$$\frac{dF}{dt} = \frac{\delta F}{\delta t} + v^\alpha F_{,\alpha}. \quad (1.5)$$

We finally note the basic M.H.D. equations, taken as⁽¹⁾

$$\begin{aligned} \frac{\partial v_i}{\partial t} + v_j v_{i,j} - \frac{\mu}{\rho} H_j H_{i,j} + \Omega_j (\Omega_i x_j - \Omega_j x_i) = \\ 2 e_{ijk} \Omega_j v_k + \frac{1}{\rho} p_{,i} = 0, \end{aligned} \quad (1.6)$$

$$\frac{\partial H_i}{\partial t} + v_j H_{i,j} - H_j v_{i,j} = 0, \quad (1.7)$$

$$v_{i,i} = 0, \quad H_{i,i} = 0. \quad (1.8,9)$$

Here (v_i) , (H_i) and (Ω_i) are the vectors of fluid velocity, magnetic field and angular velocity; (μ) is the magnetic permeability and (ρ) is the density; lastly (p) is the total pressure (the sum of hydrostatic and Magnetic pressures).

3. The Equation of Growth: We assume that (p) , (v_i) and (H_i) are continuous across $\Sigma(t)$ and the discontinuities are only in the gradients of the two vectors. Using a square bracket to denote the jumps, we write the discontinuities as

$$\begin{aligned} [v_{i,j}] n_j &= \xi_i, [H_{i,j}] n_j = \eta_i, [v_{i,jk}] n_j n_k = \bar{\xi}_i, \\ [H_{i,jk}] n_j n_k &= \bar{\eta}_i. \end{aligned} \quad (2.1)$$

The first order compatibility conditions give

$$(v_n - G) \xi_i = \frac{\mu H_n}{\rho} \eta_i, (v_n - G) \eta_i = H_n \xi_i. \quad (2.2)$$

The suffix (n) denotes the normal component. The field variables in (2.2) and now-onwards only refer to values ahead.

The above relations lead to

$$G = v_n + \sqrt{\frac{\mu}{\rho}} H_n, \xi_i = -\sqrt{\frac{\mu}{\rho}} \eta_i. \quad (2.3)$$

The equations for rays and those governing the variation of the normal (n_i) along the rays can be obtained as

$$v_i = v_i + \sqrt{\frac{\mu}{\rho}} H_i, \frac{dn_i}{dt} = (n_j n_k v_{j,k} n_i - n_j v_{j,i}). \quad (2.4)$$

Now differentiate (1.6) and (1.7) with respect to (x_i) and multiply by (n_i) . The second order compatibility conditions give

$$\begin{aligned} -G \bar{\xi}_i + \frac{\delta \bar{\xi}_i}{\delta t} + v_j (\bar{\xi}_i n_j + g^{\alpha\beta} \xi_{i,\alpha} x_{j,\beta}) - \frac{\mu}{\rho} H_j (\bar{\eta}_i n_j \\ + g^{\alpha\beta} \eta_{i,\alpha} x_{j,\beta}) + \xi_j v_{i,j} + v_{j,k} n_j n_k \bar{\xi}_i - \frac{\mu}{\rho} (H_{j,k} n_j n_k \bar{\eta}_i \\ + H_{i,j} \eta_j) + 2e_{ijk} \Omega_j \bar{\xi}_k = 0, \end{aligned} \quad (2.5)$$

$$\begin{aligned}
& -G\bar{\eta}_i + \frac{\delta\eta_i}{\delta t} + v_j(\bar{\eta}_i n_j + g^{\alpha\beta}\eta_{i,\alpha}x_{j,\beta}) - H_j(\bar{\xi}_i n_j + g^{\alpha\beta}\xi_{i,\alpha}x_{j,\beta}) \\
& + v_{j,k}n_j n_k \bar{\eta}_i + H_{i,j}\xi_j = H_{j,k}n_j n_k \bar{\xi}_i - v_{i,j}\bar{\eta}_j = 0 . \quad (2.6)
\end{aligned}$$

Using (1.4), (1.5), (2.3) and (2.4), these can be written as

$$\begin{aligned}
\sqrt{\frac{\mu}{\rho}} H_n (\bar{\xi}_i + \sqrt{\frac{\mu}{\rho}} \bar{\eta}_i) &= \frac{d\xi_i}{dt} + 2e_{ijk}\Omega_j \xi_k + v_{i,j}\xi_j \\
&+ v_{j,k}n_j n_k \bar{\xi}_i , \quad (2.7)
\end{aligned}$$

$$H_n (\bar{\xi}_i + \sqrt{\frac{\mu}{\rho}} \bar{\eta}_i) = \frac{d\eta_i}{dt} + v_{j,k}n_j n_k \bar{\eta}_i - v_{i,j}\bar{\eta}_j . \quad (2.8)$$

Eliminating the barred vectors, we obtain, by use of (2.3),

$$\frac{d\xi_i}{dt} + e_{ijk}\Omega_j \xi_k + \xi_i \frac{d \log G}{dt} = 0 . \quad (2.9)$$

Let $G \xi_i = \Psi_i$; then this equation can be written as

$$\frac{d\Psi_i}{dt} + e_{ijk}\Omega_j \Psi_k = 0 . \quad (2.10)$$

This is the final growth equation. Clearly, in absence of rotation, the rate vanishes. Rotation leads to a nonvanishing growth-rate of the discontinuity.

We always have one integral

$$\Psi_i \Psi_i = \text{constant} . \quad (2.11)$$

So the absolute magnitude of the discontinuity is constant; the discontinuity, though varying, never grows indefinitely.

We further note that the discontinuity is tangential. This property of transversality, obtained from (1.7,8), can be written as

$$\Psi_i n_i = 0 . \quad (2.12)$$

When (Ω_i) is constant, we obtain one more integral

$$\Omega_i \Psi_i = \text{constant.} \quad (2.13)$$

So for constant rotation, the three relations (2.11) (2.12) and (2.13) constitute the complete integral.

We now obtain another integral valid for arbitrary angular velocity (Ω_i) and arbitrary steady state ahead. Differentiate (2.12) along the rays and substitute from (2.4) and (2.10); we then get

$$e_{ijk} n_j \Omega_j \Psi_k + n_j \Psi_k V_{j,k} = 0 \quad (2.14)$$

Solving (2.11), (2.12) and (2.14) for (Ψ_i) , we obtain

$$\Psi_i = \frac{\Psi_0}{P} P_i \quad (2.15)$$

where Ψ_0 is the initial magnitude of (Ψ_i) and

$$P_i = \Omega_i - \Omega_j n_j n_i - e_{ijk} n_j n_p V_{p,k}, \quad P_i P_i = P^2 \quad (2.15,a)$$

This gives the complete description of the discontinuity vector (Ψ_i) in terms of its initial magnitude and of the state ahead.

Any further discussion requires the knowledge of steady-state solutions of the state ahead. We note one simple solution for which the nature of the discontinuity can be more clearly explained. Let (Ω_i) (H_i) be constant vectors with only third component as non-vanishing. Thus we take the steady-state solutions as

$$v_i = (\Omega x_2, -\Omega x_1, 0), \quad H_i(0, 0, H), \quad \Omega_i(0, 0, \Omega) \quad (2.16)$$

Let the initial wave-form be a plane normal to the 3-axis. It can

then be shown that the front remains a plane normal to 3-axis. Then the solution of (2.10) is given as

$$\begin{aligned} \Psi_1 &= \Psi_{01} \cos \Omega t + \Psi_{02} \sin \Omega t, \quad \Psi_2 = -\Psi_{01} \sin \Omega t \\ &+ \Psi_{02} \cos \Omega t, \quad \Psi_3 = 0 \end{aligned} \quad (2.17)$$

Thus the discontinuity vector rotates in the plane of the wave-front with the velocity of the fluid.

4. References:

1. S. D. Nigam and P. D. Nigam. Proc. Roy. Soc., 272, 529, (1963).
2. T. Y. Thomas. J. Math. & Mech. 6, 455, (1957).
3. R. Courant and D. Hilbert, Methods of Mathematical Physics, (Interscience Publishers, Inc. New York, 1962), Vol. 11, Chap. VI.
4. G. A. Nariboli. J. Math. Anal. Appl., 16, 108, (1966).
5. G. A. Nariboli. Memorial Volume for Prof. B. R. Seth., I.I.T. Madras (India) (To be published.)

