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# STRUCTURAL BEHAVIOR OF A PLATE RESEMBLING A CONSTANT THICKNESS BRIDGE ABUTMENT WINGWALL 

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# STRUCTURAL BEHAVIOR OF A PLATE RESEMBLING A CONSTANT THICKNESS bridge Abutment wingwall 

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[^0]Many highway and railway bridges are supported on reinforced concrete abutments similar to the one shown in figure 1. This type of abutment is used by the Iowa State Highway Commission. The wingwalls of this abutment, which may be either of constant or variable thickness, are $\rightarrow$ the vertical slabs of reinforced concrete attached to the breastwall and footings. A distributed load of varying intensity is exerted on these slabs by the lateral pressure of the soil which they retain. In addition to being retaining walls, the wingwalls also function as counterforts to the breastwall of the abutment. As might be expected, the structural action of such a wall is very complex; for that reason it does not lend itself readily to common methods of structural engineering analysis.

The practice of the Iowa State Highway Commission is to assume that the wingwall is a thin homogeneous plate which is subjected to a normal distributed load which varies linearly with depth. The commission considers the plate as fixed at the juncture to the breastwall and footing and free on the other two edges. Since such a plate has mathematical boundary conditions which are quite complex, a solution of the governing differential plate equation is not easily obtained. Most structural engineers do not have the time necessary to solve such a plate problem. Therefore bridge engineers make various additional simplifying assumptions as to the structural behavior of these wingwalls to obtain


Fig. 1. Reinforced concrete bridge abutment.
practical designs. The assumptions and the resulting designs vary greatly with individual engineers.

The first stage of this project was a literature review and a questionaire survey. A thorough and exhaustive search was made in all publications for material on the subject of bridge abutments and wingwalls. All of the several hundred available publications were reviewed; but no experimental or rigorous analytical investigations of reinforced concrete wingwalls of the type shown in figure 1 were found. The findings agreed with those of the Portland Cement Association (11, p.12) that "no structural analysis is available by which the stresses (in wingwalls) may be determined", and "suitable reinforcement may be provided by judgment or empirical rules". Letters and questionnaires similar to the ones shown in the Appendix were sent to several hundred highway, railway, and consulting engineers throughout the United States and Canada. Answers were returned by $80 \%$ of the highway engineers, $59 \%$ of the railway bridge engineers and $67 \%$ of the consulting engineers. These answers are tabulated in the Appendix.

The results of both the literature review and the survey confirm the fact that individual engineers analyze and design such wingwalls on the basis of different assumptions regarding the structural behavior of these walls. The major result of the first stage of the project was the compilation of evidence that a thorough study of this subject was needed.

The second stage of this project establishes a feasible analytical method for the solution of the type of plate problem associated with a wingwall. An aluminum plate of constant thickness, considered as a model of a typical wingwall, was studied both analytically and experimentally. An exact solution of the basic plate equation was not considered feasible because of the complex boundary conditions involved, but a numerical solution using the method of finite differences was obtained. An experimental study was made of the aluminum plate to serve as a control in determining the refinement of the numerical solution necessary to produce adequate theoretical results for $a$ particular shape of plate.

## THEORETICAL INVESTIGATION

Lagrange's differential equation governs the small deflections of a flat constant thickness thin plate which is subjected to normal distributed loads. This equation whose development may be found in various sources, ${ }^{13,15,17 \text {, may be written }}$ as follows:

$$
\begin{aligned}
& \frac{\partial^{4} w}{\partial x^{4}}+2 \frac{\partial^{4} w}{\partial x^{2}} \frac{y^{2}}{\partial y^{2}}+\frac{\partial^{4} w}{\partial y^{4}}=\frac{p}{D} \\
& \text { where } x, y
\end{aligned} \begin{aligned}
& p=\text { coordinates of a point } \\
& p=\text { intensity of distributed load at } x, y \\
& w=\text { deflection of plate at any point } x, y \\
&=\frac{E h^{3}}{12\left(1-\mu^{2}\right)} \\
& \text { and } \quad \begin{aligned}
E & =\text { modulus of elasticity } \\
h & =\text { thickness of plate } \\
\mu & =\text { Poisson's ratio }
\end{aligned}
\end{aligned}
$$

The limitations and assumptions on this equation are as follows:
a. The plate is medium-thick, i.e., not so thin that it approaches a membrane in action nor so thick that the distribution of stresses at the ends appreciably influences the results.
b. The material is homogeneous, isotropic, and perfectly elastic.
c. A straight line perpendicular to the central surface of the plate before flexure remains straight and perpendicular to that surface after flexure.
d. Stress is proportional to strain.

A solution of this equation would permit rather precise predictions of structural behavior of plates with due regard to the previous assumptions; hence this equation forms the basis for all attempts at exact solutions of plate problems. Unfortunately, it has been solved only for a few particular cases, most of which involve symmetry or simplified loading and boundary conditions. An exact mathematical solution of this differential equation for a plate of the wingwall type is difficult, if not impossible.

It was felt that for the case of a reinforced concrete wingwall, certain approximate solutions to the above equation would yield results which were as valid as those of the so-called exact solution. Some of the various approximate methods considered were the "Elastic Web", the "Trial-Load", "Moment Distribution", the Presan Photographic Model Analysis, and the Finite-Difference method.

The Elastic-Web method ${ }^{7,19}$ conceives the plate as a network of orthogonally crossed elastic wires. The loads, if of the distributed type, are replaced by equivalent concentrations at the web intersections. End conditions representing different conditions of continuity or freedom from restraint at the supports are determined from the theory of the action of elastic
webs, which follows the theory of thin membranes. The deflections of the web under various loading conditions give moments, stresses, and deflections of the plate much as the equilibrium polygon can be made to yield analagous quantities for beams. The deflections of the web are determined by means of difference equations that are easily set up. The number of the difference equations that must be solved simultaneously is usually equal to the number of web intersections.

In the Trial Load method of analysis ${ }^{16,18}$ the plate is reduced to a number of isolated beams running at right angles to each other. The load on the plate is so distributed to these crossed beams that final deflections and positions of the beams are compatible. Either a trial and error method of procedure may be used to obtain these compatible deflections or simultaneous equations may be written from which results may be obtained.

The Moment Distribution method ${ }^{4,2}$ superimposes a grid on the plate and uses a process similar to that of the familiar moment distribution in planar structures. Separate distribution must be made of the fixed end moments resulting from unit displacements for each joint. Then reactions or holding forces for each of these solutions must be calculated at these joints; and, finally, to obtain the deflections, a set of simultaneous equations which satisfy shear relationships must be solved. The number of these equations is equal to the number of node points corresponding to grid intersections.

The Presan method ${ }^{3}$ consists of building a lucite model of the plate to be analyzed and then coating one surface with reflective paint. A gridwork is constructed and placed parallel to this reflective surface some distance away. The grid is reflected by the model to a camera. When pressure is applied to the lucite plate, the reflection of the grid to the camera is distorted. Photographs of the reflected grid are taken before and after loading. From these photographs slopes of the lucite plate may be determined. Using these slopes and finite difference equations the plate may be analyzed.

The finite difference method ${ }^{17, \text { pp. } 106-143}$ is a very powerful numerical method for the approximate solution of differential equations. Its application to the Lagrange equation consists of rewriting the differential equation in terms of unknown values of the deflection at a finite number of points on the plate, usually corresponding to the intersections of superimposed grid lines. The use of this method results direct-
ly in the formulation of one simultaneous linear algebraic equation for each grid intersection or node point.

The decision was made to use this finite difference method; since simultaneous equations may be formulated directly instead of after long laborious, analogous manipulations. The highspeed digital computer has made the solution of these simultaneous equations practical, convenient, and in most cases economical.

The Lagrange plate equation as mentioned previously is:

$$
\frac{\partial^{4} w}{\partial x^{4}}+2 \frac{\partial^{4} w}{\partial x^{2} \partial y^{2}}+\frac{\partial^{4} w}{\partial y^{4}}=\frac{p}{D}
$$

f
Expressions for moments, etc. are:

$$
\begin{aligned}
\text { Moments: } M_{x} & =-D\left(\frac{\partial^{2} w}{\partial x^{2}}+\mu \frac{\partial^{2} w}{\partial y^{2}}\right) \\
M_{y} & =-D\left(\frac{\partial^{2} w}{\partial y^{2}}+\mu \frac{\partial^{2} w}{\partial x^{2}}\right) \\
M_{x y} & =M_{y x}=D(1-\mu) \frac{\partial^{2} w}{\partial x \partial y} \\
\text { Shears: } \quad Q_{x} & =-D\left(\frac{\partial^{3} w}{\partial y^{3}}+\frac{\partial^{3} w}{\partial x \partial y^{2}}\right) \\
\text { Edge Force: } \quad R_{x} & =-D\left[\frac{\partial^{3} w}{\partial x^{3}}+(2-\mu) \frac{\partial^{3} w}{\partial x \partial y^{2}}\right] \\
Q_{y} & =-D\left(\frac{\partial^{3} w}{\partial x^{3}}+\frac{\partial^{3} w}{\partial y \partial x^{2}}\right) \\
R_{y} & =-D\left[\frac{\partial^{3} w}{\partial y^{3}}+(2-\mu) \frac{\partial^{3} w}{\partial y \partial x^{2}}\right]
\end{aligned}
$$

$$
\begin{aligned}
& \text { Concentrated } \\
& \text { Corner Force: } \quad R=2 M_{x y}=2 D(1-\mu) \frac{\partial^{3} w}{\partial x \partial y}
\end{aligned}
$$

where moments and shears are for a unit length of edge and where notation and limitations are as previously stated.

The directions corresponding to positive quantities are shown in the following sketch:


Consider the following network which may be drawn on the surface of the deflected plate.


Fig. 2. Grid network.
The elevation of the section line through point o in the E-W direction may be drawn as follows:


The slope at point o may be approximated in several ways. In general, any of the following forms may be used:

$$
\begin{aligned}
& {\left[\frac{\partial w}{\partial x}\right]_{0} \doteq \frac{w_{E}-w_{0}}{\lambda} \text {, the first forward difference quotient; }} \\
& {\left[\frac{\partial w}{\partial x}\right]_{0} \doteq \frac{w_{0}-w_{w}}{\lambda} \text {, the first backward difference quotient; }} \\
& {\left[\frac{\partial w}{\partial x}\right]_{0}=\frac{w_{\varepsilon}-w_{w}}{2 \lambda}, \text { the first central difference quotient. }}
\end{aligned}
$$

For particular situations, one form may be more accurate than the others. In general, however, without any other information, there is no particular preference. The first central difference quotient will be used here.

To approximate the second derivative in the x -direction at o , again there is a choice of forms. As an obvious extension of the first central difference quotient, the second derivative may be approximated by taking the first central difference quotient of the first central difference quotient. Thus

$$
\left.\left[\frac{\partial^{2}}{\partial x_{w}^{2}}\right]_{0}\right) \frac{1}{4 \lambda^{2}}\left[\left(w_{t t}-w_{0}\right)-\left(w_{0}-w_{w w}\right)\right]
$$

However, this form involves values of w at points which are two grid points removed from the point of interest, o. The second derivative at o will obviously depend more on the values
of $w$ at E and W than at points farther removed. This factor may be taken into account by approximating the second derivative by taking the first forward difference quotient of the first backward difference quotient, or vice versa since both operations give the same form for equal grid spacings. Thus:

$$
\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{0}=\frac{1}{\lambda}\left(\frac{w_{p}-w_{0}}{\lambda}-\frac{w_{0}-w_{w}}{\lambda}\right)=\frac{1}{\lambda^{2}}\left(w_{\varepsilon}-2 w_{0}+w_{w}\right)
$$

Consistent with the above, the third derivative may be approximated by

$$
\begin{aligned}
{\left[\frac{\partial^{3} w}{\partial x^{3}}\right]_{0} } & =\frac{1}{2 \lambda}\left[\frac{1}{\lambda^{2}}\left(w_{\varepsilon \in}-2 w_{\xi}+w_{0}\right)-\frac{1}{\lambda^{2}}\left(w_{0}-2 w_{w}+w_{w w}\right)\right] \\
& =\frac{1}{2 \lambda^{3}}\left(w_{\varepsilon E}-2 w_{E}+2 w_{w}-w_{w w}\right)
\end{aligned}
$$

and the fourth derivative by

$$
\begin{aligned}
{\left[\frac{\partial^{4} w}{\partial x^{4}}\right]_{0} } & =\frac{1}{\lambda^{2}}\left[\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{E}-2\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{0}+\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{w}\right] \\
& =\frac{1}{\lambda^{4}}\left[\left(w_{\varepsilon E}-2 w_{E}+w_{o}\right)-2\left(w_{E}-2 w_{0}+w_{w}\right)+\left(w_{0}-2 w_{w}+w_{w w}\right)\right] \\
& \doteq \frac{1}{\lambda^{4}}\left(w_{E E}-4 w_{E}+6 w_{0}-4 w_{w}+w_{w w}\right)
\end{aligned}
$$

The mixed second derivative may be approximated by

$$
\begin{aligned}
{\left[\frac{\partial^{2} w}{\partial \times \partial y}\right]_{0} } & =\frac{1}{2 \lambda}\left[\left(\frac{w_{S E}-w_{s w}}{\lambda^{2}}\right)-\left(\frac{w_{N E}-w_{N w}}{\lambda^{2}}\right)\right] \\
& =\frac{1}{2 \lambda^{3}}\left(w_{S E}-w_{N E}-w_{s w}+w_{N w}\right)
\end{aligned}
$$

The mixed fourth derivative becomes

$$
\begin{aligned}
{\left[\frac{\partial^{4} w}{\partial x^{2} \partial_{y}^{2}}\right]_{0} } & =\frac{1}{2}\left\{\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{s}-2\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{0}+\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{N}\right\} \\
& =\frac{1}{\lambda^{2}}\left[\left(\frac{w_{S t}-2 w_{s}+w_{s w}}{\lambda^{2}}\right)-i\left(\frac{w_{s}-2 w_{0}+w_{w}}{\lambda^{2}}\right)+\left(\frac{w_{N E}-2 w_{N}+w_{N w}}{\lambda^{2}}\right)\right] \\
& =\frac{1}{\lambda^{4}}\left[w_{N E}+w_{s E}+w_{s w}+w_{N w}-2\left(w_{N}+w_{s}+w_{E}+w_{w}\right)+4 w_{0}\right]
\end{aligned}
$$

Hence the approximate values of the partial derivatives at point o may be written in terms of the deflection at $o$ and neighboring points with reference to figure 2 as follows:

$$
\begin{aligned}
& {\left[\frac{\partial w}{\partial x}\right]_{0}=\frac{1}{2 \lambda}\left(w_{E}-w_{w}\right)} \\
& {\left[\frac{\partial^{2} w}{\partial x^{2}}\right]_{0}=\frac{1}{\lambda^{2}}\left(w_{E}-2 w_{0}+w_{w}\right)} \\
& {\left[\frac{\partial^{3} w}{\partial x^{3}}\right]_{0}=\frac{1}{2 \lambda^{3}}\left(w_{E E}-2 w_{E}+2 w_{w}-w_{w w}\right)} \\
& {\left[\frac{\partial^{4} w}{\partial x^{4}}\right]_{0}=\frac{1}{\lambda^{4}}\left(w_{E G}-4 w_{E}+6 w_{0}-4 w_{w}+w_{w w}\right)} \\
& {\left[\frac{\partial w}{\partial y}\right]_{0}=\frac{1}{2 \lambda}\left(w_{g}-w_{w}\right)}
\end{aligned}
$$

$$
\begin{aligned}
& {\left[\frac{\partial^{2} w}{\partial y^{2}}\right]_{0}=\frac{1}{\lambda^{2}}\left(w_{s}-2 w_{0}+w_{N}\right)} \\
& {\left[\frac{\partial^{3} w}{\partial y^{3}}\right]_{0}=\frac{1}{2 \lambda^{2}}\left(w_{s g}-2 w_{s}+2 w_{N}-w_{N N}\right)} \\
& {\left[\begin{array}{l}
\partial^{4} w \\
\partial y^{4}
\end{array}\right]_{0}=\frac{1}{\lambda^{4}}\left(w_{s \in}-4 w_{s}+6 w_{0}-4 w_{N}+w_{N N}\right)} \\
& {\left[\frac{\partial^{2} w}{\partial x \partial y}\right]_{0}=\frac{1}{4 \lambda^{2}}\left(w_{s E}-w_{N E}-w_{s w}+w_{N w}\right)} \\
& {\left.\left[\frac{\partial^{4} w}{\partial x^{2} \partial y^{2}}\right]_{0}=\frac{1}{\lambda^{4}} \right\rvert\, w_{N E}+w_{s E}+w_{s w}+w_{N w}} \\
& \left.-2\left(w_{N}+w_{s}+w_{E}+w_{w}\right)+4 w_{0}\right]
\end{aligned}
$$

Where $\lambda=$ Spacing of square network (in.).
If these approximate values of derivatives are substituted into the appropriate differential equations from the plate theory, the following expressions result:

$$
\begin{aligned}
& \text { Load: } 20 w_{0}-8\left(w_{n}+w_{6}+w_{s}+w_{w}\right) \\
& +2\left(w_{\mathbf{N E}}+w_{\mathbf{g W}}+w_{\mathbf{g w}}+w_{N w}\right) \\
& +w_{N N}+w_{E E}+w_{g S}+w_{w w}=\frac{p_{0} \lambda^{4}}{D} \\
& \text { Moments: }\left(M_{x}\right)_{0}=-\frac{D}{\lambda^{2}}\left[-(2+2 \mu) w_{0}+w_{w}\right. \\
& \left.+w_{E}+\mu\left(w_{N}+w_{s}\right)\right] \\
& \left(M_{y}\right)_{o}=-\frac{D}{\lambda^{2}}\left[-(2+2 \mu) w_{0}+w_{N} .\right. \\
& \left.+w_{s}+\mu\left(w_{w}+w_{\boldsymbol{z}}\right)\right] \\
& \left(M_{x y}\right)_{o}=\frac{D(1-\mu)}{4 \lambda^{2}}\left(w_{s E}-w_{N E}-w_{s w}+w_{N w}\right) \\
& \text { Shears: }\left(\rho_{x}\right)_{0}=-\frac{D}{2 \lambda^{3}}\left[4\left(w_{w}-w_{E}\right)+w_{N E}+w_{B E}\right. \\
& \left.-w_{N w}-w_{B w}-w_{w W}+w_{G E}\right) \\
& \left.\left(Q_{y}\right)_{0} \cdots \frac{D}{2 \lambda^{3}} \right\rvert\, 4\left(w_{N}-w_{s}\right)+w_{s e}+w_{s w} \\
& \text { Edge Forces: } \left.\left(R_{\mathbf{x}}\right)_{0}=-\frac{\mathrm{D}}{2 \lambda^{3}} \right\rvert\,(6-2 \mu)\left(w_{w}-w_{E}\right) \\
& \left.+(2-\mu)\left(w_{w E}+w_{s E}-w_{N w}-w_{s w}\right)-w_{w w}+w_{f E}\right] \\
& \left(R_{y}\right)_{0}=-\frac{D}{2 \lambda^{3}}\left[(6-2 \mu)\left(w_{N}-w_{s}\right)\right. \\
& \left.+(2-\mu)\left(w_{\mathbf{s E}}+w_{\mathbf{B W}}-w_{\mathbf{N W}}-w_{\mathbf{N E}}\right)-w_{\mathbf{w N}}+w_{\mathbf{B S}}\right]
\end{aligned}
$$

Corner Force: ( R$)_{\text {。 }}$

$$
=\frac{D(1-\mu)}{2 \lambda^{2}}\left(w_{s E}-w_{N E}-w_{s w}^{*}+w_{N w}\right)
$$

The boundary conditions to be considered here correspond to those for fixed and free edges. Conditions which are assumed on these boundaries are specified on the following page.

2. Free Edge on which $y=$ constant:

$$
\begin{array}{ll}
\text { Moment Zero: } & \mathrm{M}_{\mathrm{y}}=0=\frac{\partial^{2} \mathrm{w}}{\partial \mathrm{y}^{2}}+\mu \frac{\partial^{2} \mathrm{w}}{\partial \mathrm{x}^{2}} \\
\text { Edge Forces: } & \mathrm{R}_{\mathrm{y}} \\
& =-\mathrm{D}\left[\frac{\partial^{3} \mathrm{w}}{\partial \mathrm{y}^{3}}+(2-\mu) \frac{\partial^{3} \mathrm{w}}{\partial \mathrm{y} \partial \mathrm{x}^{2}}\right]
\end{array}
$$

3. Free Corner:
Moment Zero: $M_{x}=M_{y}=0 ; \frac{\partial^{2} w}{\partial x^{2}}$

$$
=\frac{\partial^{2} w}{\partial y^{2}}=0
$$

f Edge Force: $\quad \mathrm{R}_{\mathrm{x}}$

$$
\begin{aligned}
&=-D\left[\frac{\partial^{3} w}{\partial x^{3}}+(2-\mu) \frac{\partial^{3} w}{\partial y^{2} \partial x}\right] \\
& R_{y}=-D\left[\frac{\partial^{3} w}{\partial y^{3}}+(2-\mu) \frac{\partial^{3} w}{\partial y \partial x^{2}}\right] \\
& \text { Corner Force: } \quad R=2 D(1-\mu) \frac{\partial^{2} w}{\partial x \partial y}
\end{aligned}
$$

In terms of finite differences, these boundary conditions may be expressed as,

$$
\begin{aligned}
& \text { 1. Fixed Edge on which } y=\text { zero: } \\
& w_{o}=0 \\
& w_{k}-w_{w}=0 \\
& \text { 2. Free Edge on which } y=\text { constant: } \\
& -(2+2 \mu) w_{0}+w_{N}+w_{s}+\mu\left(w_{w}+w_{z}\right)=0 \\
& (6 i-2 \mu)\left(w_{N}-w_{s}\right) \\
& +(2-\mu)\left(w_{B E}+w_{B W}-w_{N W}-w_{N E}\right)-w_{N N} \\
& +w_{s \mathrm{~s}}=-\frac{2 \lambda^{3}\left(R_{y}\right)_{o}}{D} \\
& \text { 3. Free Corner: } \\
& w_{k}-2 w_{o}+w_{w}=0 \\
& w_{B}-2 w_{O}+w_{N}=0 \\
& (6-2 \mu)\left(w_{w}-w_{z}\right) \\
& +(2-\mu)\left(w_{N E}+w_{B E}-w_{N W}-w_{s w}\right) \\
& -w_{w w}+w_{E E}=-\frac{2 \lambda^{3}\left(R_{x}\right)_{0}}{D} \\
& (6-2 \mu)\left(w_{N}-w_{s}\right) \\
& +(2-\mu)\left(w_{\text {se }}+w_{B W}-w_{N W}-w_{N E}\right)-w_{N N} \\
& +w_{s 8}=-\frac{2 \lambda^{3}\left(R_{y}\right)_{o}}{D} \\
& w_{S E}-w_{N E}-w_{s w}+w_{N W}=\frac{2 \lambda^{2}(R)_{0}}{D(1-\mu)}
\end{aligned}
$$

Since $w_{0}$ in each boundary condition is for a point on the edge of the plate, it is apparent that some of the deflections indicated are fictitious ones lying off the plate. To indicate the procedure used to express these fictitious deflections in terms of real ones let us consider the
example of a point on the edge where $y=$ constant. One may see from the diagrams below that there are deflections at four points off the plate in the equation for the edge force.


The fictitious deflections are $\mathrm{w}_{\mathrm{sw}}, \mathrm{w}_{\mathrm{s}}, \mathrm{w}_{\mathrm{se}}$, and $\mathrm{w}_{\text {ss }}$.
These fictitious deflections may be evaluated in terms of the deflections of the plate so that the conditions for a free edge can be determined in terms of deflections at points on the plate. Since four quantities are to be eliminated, five conditions are specified along the free edge. They are:

$$
\begin{aligned}
& \text { 1. Load: } 20 w_{o}-8\left(w_{N}+w_{\mathbf{w}}+w_{\mathbf{g}}+w_{w}\right) \\
& +2\left(w_{N W}+w_{N E}+w_{s E}+w_{s w}\right)+w_{w W}+w_{N N} \\
& +w_{E E}+w_{B g}=\frac{P_{O} \lambda^{4}}{D} \\
& \text { 2. Edge Force: }(6-2 \mu)\left(w_{N}-w_{s}\right) \\
& +(2-\mu)\left(w_{\mathbf{B E}}+w_{\mathbf{B W}}-w_{N W}-w_{N E}\right) \\
& -w_{N N}+w_{s g}=-\frac{2 \lambda^{3}\left(R_{y}\right)_{o}}{D} \\
& \text { 3. Moment at } o \text { : }-(2+2 \mu) w_{o}+w_{N}+w_{s} \\
& +\mu\left(w_{w}+w_{E}\right)=0 \\
& \text { Moment at } w:-(2+2 \mu) w_{w}+w_{N w}+w_{s w} \\
& +\mu\left(w_{w w}+w_{o}\right)=0 \\
& \text { Moment at: }-(2+2 \mu) w_{E}+w_{w z}+w_{s t} \\
& +\mu\left(w_{E E}+w_{o}\right)=0 \\
& \text { (For an edge with no loading } p_{o}=\left(R_{y}\right)_{o}=0 \text { ) }
\end{aligned}
$$

Eliminating $\mathrm{w}_{\mathrm{ss}}, \mathrm{w}_{\mathrm{sw}}, \mathrm{w}_{\mathrm{se}}$, and $\mathrm{w}_{\mathrm{s}}$ from these equations gives:

$$
\begin{array}{r}
\left(16-8 \mu-6 \mu^{2}\right) w_{0}+(-12+4 \mu) w_{N} \\
\left.+\left(-8+4 \mu+4 \mu^{2}\right) w_{w}+w_{E}\right)+(4-2 \mu) \\
\left(w_{N E}+w_{N w}\right)+\left(1-\mu^{2}\right)\left(w_{w w}+w_{E E}\right) \\
+2 w_{N N}=\frac{p_{0} \lambda^{4}}{D}+\frac{2 \lambda^{3}\left(R_{y}\right)_{0}}{D}
\end{array}
$$

The equation for this edge condition may be schematically represented as follows:


This procedure was followed for all typical points of a plate resembling a wingwall (with simplified upper edge) and the various quantities were evaluated for $\mu=0.30$. Resulting coefficient patterns for these typical points are


Fig. 3. Finite difference equation coefficient patterns for deflection ( $\mu=0.30$ ).


Fig. 3 cont'd. Finite difference equation coefficient patterns for deflection ( $\mu=0.30$ ).

As stated, the finite difference method usually involves one independent equation for each point that is used as a node point in the superimposed grid. The type of grid used is usually rectangular. It follows that the method must be modified for non-rectangular plates. A method has been presented ${ }^{17, ~ p . ~} 138$ by which the difference equations may be adjusted at irregular edges, but such a method is tedious. It has been applied to skew slabs ${ }^{5,10}$ using oblique coordinates. Since the loading approached zero at the sloping edge, it was convenient to assume the plate rectangular (figure 4). This simplification greatly facilitated the application of the finite difference method in that the theoretical plate was then rectangular (actually square in this case) instead of trapezoidal. It was found that results from this simplified plate varied little from those obtained by a more refined consideration of the sloping edge involving the double Laplacian form of the plate equation.

An infinite number of grid patterns may be superimposed on a plate. The smaller the grid spacing used, the greater will be the number of simultaneous equations obtained, and the more closely their solutions should approximate that of a rigorous mathematical solution of the differential equation. Solutions were desired for sets of equations resulting from the application
of the finite difference method to grids of $2 \times 2$, $3 \times 3,4 \times 4,5 \times 5,6 \times 6$, and $7 \times 7$ as shown in figures 5 to 10 . It was decided that a comparison of solutions for these sets of equations with experimental results would give an indication of the size of grid that must be used on a thin plate of specified proportion to obtain reasonable predictions of structural behavior. The equations corresponding to the different grid spacings follow:


Fig. 4. Theoretical approximation of sloping edge.
$=14.00000$

| $11-20 w_{11}-5.4 w_{12}-5.4 w_{21}+1.4 w_{22}$ | $=14.00000$ |
| :--- | :--- |
| $12-10.8 w_{11}+3.4 w_{21}-4.62 w_{22}+13.06 w_{12}$ | $=9.00000$ |
|  |  |
| $21-10.8 w_{11}+3.4 w_{12}-4.62 w_{22}+13.06 w_{21}$ |  |

$\begin{array}{ll}21-10.8 w_{11}+3.4 w_{12}-4.62 w_{22}+13.06 w_{21} \\ 22 & 9.24 w_{22}-9.24 w_{12}-9.24 w_{21}+5.6 w_{11}\end{array}$
$=0.00000$

Node
Equation
$3 \times 3$
$22 w_{11}-8 w_{12}+w_{13}-8 w_{21}+2 w_{22}+w_{31}$
$-8 w_{11}+20 w_{12}-5.4 w_{13}+2 w_{21}-8 w_{22}+1.7 w_{23}+w_{32}$
$2 w_{11}-10.8 w_{12}+13.97 w_{13}+3.4 w_{22}-6.44 w_{23}+0.91 w_{33}$
$-8 w_{11}+2 w_{12}+20 w_{21}-8 w_{22}+w_{23}-5.4 w_{31}+1.7 w_{32}$
$2 w_{11}-8 w_{12}+1.7 w_{13}-8 w_{21}+18 w_{22}-5.4 w_{23}+1.7 w_{31}-5.4 w_{32}+1.4 w_{33}$
$2 w_{11}-8 w_{12}+1.7 w_{13}-8 w_{21}+18 w_{22}-5.4 w_{23}+1.7 w_{31}$
$3.4 w_{12}-6.44 w_{13}+2 w_{21}-10.8 w_{22}+12.15 w_{23}+3.4 w_{32}-4.62 w_{33}$
$-10.8 w_{21}+3.4 w_{22}+13.97 w_{31}-6.44 w_{32}+0.91 w_{33}$
$2 w_{12}+3.4 w_{21}-10.8 w_{22}+3.4 w_{23}-6.44 w_{31}+12.15 w_{32}-4.62 w_{33}$
$31.82 w_{13}+5.6 w_{22}-9.24 w_{23}+1.82 w_{31}+9.24 w_{33}$

| Node | Equation |
| :---: | :---: |
| $4 \times 4$ |  |
|  | $22 w_{11}-8 w_{12}+w_{13}-8 w_{21}+2 w_{22}+w_{31}$ |
| 12 | $-8 w_{11}+21 w_{12}-8 w_{13}+w_{14}+2 w_{21}-8 w_{22}+2 w_{23}+w_{32}$ |
|  | $w_{11}-8 w_{12}+20 w_{13}-5.4 w_{14}+2 w_{22}-8 w_{23}+1.7 w_{24}+w_{33}$ |
|  | $2 w_{12}-10.8 w_{13}+13.97 w_{14}+3.4 w_{23}-6.44 w_{24}+0.91 w_{34}$ |
| 21 | $-8 w_{11}+2 w_{12}+21 w_{21}-8 w_{22}+w_{23}-8 w_{31}+2 w_{32}+w_{41}$ |
| 22 | $2 w_{11}-8 w_{12}+2 w_{13}-8 w_{21}+20 w_{22}-8 w_{23}+w_{24}+2 w_{31}-8 w_{32}+2 w_{33}+w_{43}$ |
| 23 | $2 w_{12}-8 w_{13}+1.7 w_{14}+w_{21}-8 w_{22}+19 w_{23}-5.4 w_{24}+2 w_{32}-8 w_{33}+1.7 w_{34}+w_{43}$ |
| 24 | $3.4 w_{13}-6.44 w_{14}+2 w_{22}-10.8 w_{23}+13.06 w_{24}+3.4 w_{33}-6.44 w_{41}+0.91 w_{44}$ |
| 31 w | $w_{11}-8 w_{21}+2 w_{22}+20 w_{31}-8 w_{32}+w_{33}-5.4 w_{41}+1.7 w_{42}$ |
| 32 | $w_{12}+2 w_{21}-8 w_{22}+2 w_{23}-8 w_{31}+19 w_{32}-8 w_{33}+w_{34}+1.7 w_{41}-5.4 w_{42}+1.7 w_{43}$ |
| 33 w | $w_{13}+2 w_{22}-8 w_{23}+1.7 w_{24}+w_{31}-8 w_{32}+18 w_{33}-5.4 w_{34}+1.7 w_{42}-5.4 w_{43}+1.4 w_{4}$ |
| 34 | $0.91 w_{14}+3.4 w_{23}-6.44 w_{24}+2 w_{32}-10.8 w_{33}+12.15 w_{34}+3.4 w_{43}-4.62 w_{44}$ |
| 41 | $2 w_{21}-10.8 w_{31}+3.4 w_{32}+13.97 w_{41}-6.44 w_{42}+0.91 w_{43}$ |
| 42 | $2 w_{22}+3.4 w_{31}-10.8 w_{32}+3.4 w_{33}-6.44 w_{41}+13.06 w_{42}-6.44 w_{43}+0.91 w_{44}$ |
| 43 | $2 w_{23}+3.4 w_{32}-10.8 w_{33}+3.4 w_{34}+0.91 w_{41}-6.44 w_{42}+12.15 w_{43}-4.62 w_{44}$ |
| 44 | $1.82 w_{24}+5.6 w_{33}-9.24 w_{34}+1.82 w_{42}-9.24 w_{43}+9.24 w_{44}$ |


| Node | Equation |
| :---: | :---: |
| $5 \times 5$ |  |
|  | $22 w_{11}-8 w_{12}+w_{13}-8 w_{21}+2 w_{22}+w_{31}$ |
| 12 - | $-8 w_{11}+21 w_{12}-8 w_{13}+w_{14}+2 w_{21}-8 w_{22}+2 w_{23}+w_{32}$ |
|  | $w_{11}-8 w_{12}+21 w_{13}-8 w_{14}+w_{15}+2 w_{22}-8 w_{23}+2 w_{24}+w_{33}$ |
| 14 w | $w_{12}-8 w_{13}+20 w_{14}-5.4 w_{15}+2 w_{23}-8 w_{24}+1.7 w_{25}+w_{34}$ |
| 152 | $2 w_{13}-10.8 w_{14}+13.97 w_{15}+3.4 w_{24}-6.44 w_{25}+0.91 w_{35}$ |
| - $21-$ | $-8 w_{11}+2 w_{12}+21 w_{21}-8 w_{22}+w_{23}-8 w_{31}+2 w_{32}+w_{41}$ |
| 22 | $2 w_{11}-8 w_{12}+2 w_{13}-8 w_{21}+20 w_{22}-8 w_{23}+w_{24}+2 w_{31}-8 w_{32}+2 w_{34}+w_{42}$ |
| 232 | $2 w_{12}-8 w_{13}+2 w_{14}+w_{21}-8 w_{22}+20 w_{23}-8 w_{24}+w_{25}+2 w_{32}-8 w_{33}+2 w_{34}+w_{43}$ |
| 24 | $2 w_{13}-8 w_{14}+1.7 w_{15}+w_{22}-8 w_{23}+19 w_{24}-5.4 w_{25}+2 w_{33}-8 w_{34}+1.7 w_{35}+w_{44}$ |
| 253 | $3.4 w_{14}-6.44 w_{15}+2 w_{23}-10.8 w_{24}+13.06 w_{25}+3.4 w_{34}-6.44 w_{35}+0.91 w_{45}$ |
| 31 w | $w_{11}-8 w_{21}+2 w_{22}+21 w_{31}-8 w_{32}+w_{33}-8 w_{41}+2 w_{42}+w_{51}$ |
| 32 w | $w_{12}+2 w_{21}-8 w_{22}+2 w_{23}-8 w_{31}+20 w_{32}-8 w_{33}+w_{34}+2 w_{41}-8 w_{42}+2 w_{43}+w_{52}$ |
| 33 w | $w_{13}+2 w_{22}-8 w_{23}+2 w_{24}+w_{31}-8 w_{32}+20 w_{33}-8 w_{34}+w_{35}+2 w_{42}-8 w_{43}+2 w_{44}+w_{53}$ |
| 34 w | $w_{14}+2 w_{23}-8 w_{24}+1.7 w_{25}+w_{32}-8 w_{33}+19 w_{34}-5.4 w_{35}+2 w_{43}-8 w_{44}+1.7 w_{45}+w_{54}$ |
| 350 | $0.91 w_{15}+3.4 w_{24}-6.44 w_{25}+2 w_{33}-10.8 w_{34}+13.06 w_{35}+3.4 w_{44}-6.44 w_{45}+0.91 w_{55}$ |
| $41^{\circ}$ w | $w_{21}-8 w_{31}+2 w_{32}+20 w_{41}-8 w_{42}+w_{43}-5.4 w_{51}+1.7 w_{52}$ |
| 42 w | $w_{22}+2 w_{31}-8 w_{32}+2 w_{33}-8 w_{41}+19 w_{42}-8 w_{43}+w_{44}+1.7 w_{51}-5.4 w_{52}+1.7 w_{53}$ |
| 43 w | $w_{23}+2 w_{32}-8 w_{33}+2 w_{34}+w_{41}-8 w_{42}+19 w_{43}-8 w_{44}+w_{45}+1.7 w_{52}-5.4 w_{53}+1.7 w_{54}$ |
| 44 w | $w_{24}+2 w_{33}-8 w_{34}+1.7 w_{35}+w_{42}-8 w_{43}+18 w_{44}-5.4 w_{45}+1.7 w_{53}-5.4 w_{54}+1.4 w_{55}$ |
| 450 | $0.91 w_{25}+3.4 w_{34}-6.44 w_{35}+2 w_{43}-10.8 w_{44}+12.15 w_{45}+3.4 w_{54}-4.62 w_{55}$ |
|  | $2 w_{31}-10.8 w_{41}:+3.4 w_{42}+13.97 w_{51}-6.44 w_{52}+0.91 w_{53}$ |
| 52 2 | $2 w_{32}+3.4 w_{41}-10.8 w_{42}+3.4 w_{43}-6.44 w_{51}+13.06 w_{52}-6.44 w_{53}+0.91 w_{54}$ |
| 53 | $2 w_{33}+3.4 w_{42}-10.8 w_{43}+3.4 w_{44}+0.91 w_{51}-6.44 w_{52}+13.06 w_{53}-6.44 w_{54}+0.91 w_{55}$ |
| 54 | $2 w_{34}+3.4 w_{43}-10.8 w_{44}+3.4 w_{45}+0.91 w_{52}-6.44 w_{53}+12.15 w_{54}-4.62 w_{55}$ |
| 551 | $1,82 w_{35}+5.6 w_{44}-9.24 w_{45}+1.82 w_{53}-9.24 w_{54}+9.24 w_{55}$ |

Node
$6 \times 6$
Equation
$22 w_{11}-8 w_{12}+w_{13}-8 w_{21}+2 w_{22}+w_{31}$
$-8 w_{11}+21 w_{12}-8 w_{13}+w_{14}+2 w_{21}-8 w_{22}+2 w_{23}+w_{32}$
$13 w_{11}-8 w_{12}+21 w_{13}-8 w_{14}+w_{15}+2 w_{22}-8 w_{23}+2 w_{24}+w_{33}$
$4 w_{12}-8 w_{13}+21 w_{14}-8 w_{15}+w_{16}+2 w_{23}-8 w_{24}+2 w_{25}+w_{34}$
$5 w_{13}-8 w_{14}+20 w_{15}-5.4 w_{16}+2 w_{24}-8 w_{25}+1.7 w_{26}+w_{35}$
$162 w_{14}-10.8 w_{15}+13.97 w_{16}+3.4 w_{25}-6.44 w_{26}+0.91 w_{36}$
$=0.05761$
$=0.05409$
$=0.05058$
$=0.04707$
$=0.04356$
$=0,04005$


Fig. 5. Node notation for $2 \times 2$ grid.


Fig. 6. Node notation for $3 \times 3$ grid.


Fig. 7. Node notation for $4 \times 4$ grid.

|  | $-8 w_{11}+2 w_{12}+21 w_{21}-8 w_{22}+w_{23}-8 w_{31}+2 w_{32}+w_{41}$ | 0.04707 |
| :---: | :---: | :---: |
|  | $2 w_{11}-8 w_{12}+2 w_{13}-8 w_{21}+20 w_{22}-8 w_{23}+w_{24}+2 w_{31}-8 w_{32}+2 w_{33}+w_{42}$ | . 04356 |
| 23 | $2 w_{12}-8 w_{13}+2 w_{14}+w_{21}-8 w_{22}+20 w_{23}-8 w_{24}+w_{25}+2 w_{32}-8 w_{33}+2 w_{34}+w_{43}$ | 05 |
| 24 | $2 w_{13}-8 w_{14}+2 w_{15}+w_{22}-8 w_{23}+20 w_{24}-8 w_{25}+w_{26}+2 w_{33}-8 w_{34}+2 w_{35}+w_{44}$ | 5 |
| 25 | $2 w_{14}-8 w_{15}+1.7 w_{16}+w_{23}-8 w_{24}+19 w_{25}-5.4 w_{26}+2 w_{34}-8 w_{35}+1.7 w_{36}+w_{45}$ | 2 |
| 26 | $3.4 w_{15}-6.44 w_{16}+2 w_{24}-10.8 w_{25}+13.06 w_{26}+3.4 w_{35}-6.44 w_{36}+0.91 w_{46}$ | 0.02951 |
| 31 | $w_{11}-8 w_{21}+2 w_{22}+21 w_{31}-8 w_{32}+w_{33}-8 w_{41}+2 w_{42}+w_{51}$ | . 03653 |
| 32 | $w_{12}+2 w_{21}-8 w_{22}+2 w_{23}-8 w_{31}+20 w_{32}-8 w_{33}+w_{34}+2 w_{41}-8 w_{42}+2 w_{43}+w_{52}$ | 3302 |
| 33 | $w_{13}+2 w_{22}-8 w_{23}+2 w_{24}+w_{31}-8 w_{32}+20 w_{33}-8 w_{34}+w_{35}+2 w_{42}-8 w_{43}+2 w_{44}+w_{53}$ | 02951 |
| 34 | $w_{14}+2 w_{23}-8 w_{24}+2 w_{25}+w_{32}-8 w_{33}+20 w_{34}-8 w_{35}+w_{36}+2 w_{43}-8 w_{44}+2 w_{45}+w_{54}$ | 02599 |
| 35 | $w_{15}+2 w_{24}-8 w_{25}+1.7 w_{26}+w_{33}-8 w_{34}+19 w_{35}-5.4 w_{36}+2 w_{44}-8 w_{45}+1.7 w_{46}+w_{55}$ | 8 |
| 36 | $0.91 w_{16}+3.4 w_{25}-6.44 w_{26}+2 w_{34}-10.8 w_{35}+13.06 w_{36}+3.4 w_{45}-6.44 w_{46}+0.91 w_{56}$ | . 01897 |
| 41 | $w_{21}-8 w_{31}+2 w_{3}+21 w_{41}-8 w_{42}+w_{43}-8 w_{51}+2 w_{52}+w_{61}$ | 02599 |
| 42 | $w_{22}+2 w_{31}-8 w_{32}+2 w_{33}-8 w_{41}+20 w_{42}-8 w_{43}+w_{44}+2 w_{51}-8 w_{52}+2 w_{53}+w_{62}$ | 02248 |
| 43 | $w_{23}+2 w_{32}-8 w_{33}+2 w_{34}+w_{41}-8 w_{42}+20 w_{43}-8 w_{44}+w_{45}+2 w_{52}-8 w_{53}+2 w_{54}+w_{63}$ | 01897 |
| 44 | $w_{24}+2 w_{33}-8 w_{34}+2 w_{35}+w_{42}-8 w_{43}+20 w_{44}-8 w_{45}+w_{46}+2 w_{53}-8 w_{54}+2 w_{55}+w_{64}$ | 46 |
| 45 | $w_{25}+2 w_{34}-8 w_{35}+1.7 w_{36}+w_{43}-8 w_{44}+19 w_{45}-5.4 w_{46}+2 w_{54}-8 w_{55}+1.7 w_{56}+w_{65}$ | 94 |
| 46 | $0.91 w_{26}+3.4 w_{35}-6.44 w_{36}+2 w_{44}-10.8 w_{45}+13.06 w_{46}+3.4 w_{55}-6.44 w_{56}+0.91 w_{66}$ | 3 |
| 51 | $w_{31}-8 w_{41}+2 w_{42}+20 w_{51}-8 w_{52}+w_{53}-5.4 w_{61}+1.7 w_{62}$ | . 01546 |
| 52 | $w_{32}+2 w_{41}-8 w_{42}+2 w_{43}-8 w_{51}+19 w_{52}-8 w_{53}+w_{54}+1.7 w_{61}-5.4 w_{62}+1.7 w_{63}$ | 0.01194 |
| 53 | $w_{33}+2 w_{42}-8 w_{43}+2 w_{44}+w_{51}-8 w_{52}+19 w_{53}-8 w_{54}+w_{55}+1.7 w_{62}-5.4 w_{63}+1.7 w_{64}$ | 43 |
| 54 | $w_{34}+2 w_{43}-8 w_{44}+2 w_{45}+w_{52}-8 w_{53}+19 w_{54}-8 w_{55}+w_{56}+1.7 w_{63}-5.4 w_{64}+1.7 w_{65}$ | 0492 |
| 55 | $w_{35}+2 w_{44}-8 w_{45}+1.7 w_{46}+w_{53}-8 w_{54}+18 w_{55}-5.4 w_{56}+1.7 w_{64}-5.4 w_{65}+1.4 w_{66}$ | 1 |
| 56 | $0.91 w_{36}+3.4 w_{45}-6.44 w_{46}+2 w_{54}-10.8 w_{55}+12.15 w_{56}+3.4 w_{65}-4.62 w_{66}$ | 00 |
| 61 | $2 w_{41}-10.8 w_{51}+3.4 w_{52}+13.97 w_{61}-6.44 w_{62}+0.91 w_{63}$ | . 00492 |
| 62 | $2 w_{42}+3.4 w_{51}-10.8 w_{52}+3.4 w_{53}-6.44 w_{61}+13.06 w_{62}-6.44 w_{63}+0.91 w_{64}$ | 0.00141 |
| 63 | $2 w_{43}+3.4 w_{52}-10.8 w_{53}+3.4 w_{54}+0.91 w_{61}-6.44 w_{62}+13.06 w_{63}-6.44 w_{64}+0.91 w_{65}$ | 000 |
|  | $2 w_{44}+3.4 w_{53}-10.8 w_{54}+3.4 w_{55}+0.91 w_{62}-6.44 w_{63}+13.06 w_{64}-6.44 w_{65}+0.91 w_{66}$ | 0.00000 |
| 65 | $2 w_{45}+3.4 w_{54}-10.8 w_{55}+3.4 w_{56}+0.91 w_{63}-6.44 w_{64}+12.15 w_{65}-4.62 w_{66}$ | 0.00000 |
| 66 | $1.82 w_{46}+5.6 w_{55}-9.24 w_{56}+1.82 w_{64}-9.24 w_{65}+9.24 w_{66}$ | 000 |


| Equation |  |  |
| :--- | :--- | :--- |
| Node | Equ |  |
| $7 \times 7$ |  |  |
| 11 | $22 w_{11}-8 w_{21}-8 w_{12}+w_{13}+w_{31}+2 w_{22}$ |  |
| 12 | $21 w_{12}-8 w_{11}-8 w_{13}-8 w_{22}+2 w_{21}+2 w_{23}+w_{32}+w_{14}$ | $=0.03218$ |
| 13 | $21 w_{13}-8 w_{12}-8 w_{14}-8 w_{23}+2 w_{22}+2 w_{24}+w_{35}+w_{15}+w_{11}$ | $=0.02859$ |
| 14 | $21 w_{14}-8 w_{13}-8 w_{15}-8 w_{24}+2 w_{23}+2 w_{23}+w_{34}+w_{16}+w_{12}$ | $=0.02730$ |
| 15 | $21 w_{15}-8 w_{14}-8 w_{16}-8 w_{25}+2 w_{24}+2 w_{26}+w_{35}+w_{17}+w_{13}$ | $=0.02568$ |
| 16 | $20 w_{16}-8 w_{15}-8 w_{26}-5.4 w_{17}+2 w_{25}+1.7 w_{27}+w_{14}+w_{36}$ | $=0.02406$ |
| 17 | $13.97 w_{17}-10.8 w_{16}-6.44 w_{27}+3.4 w_{26}+2 w_{15}+0.91 w_{37}$ | $=0.02243$ |
|  |  |  |



Fig. 8. Node notation for $5 \times 5$ grid.


Fig. 9. Node notation for $6 \times 6$ grid.


Fig. 10. Node notation for $7 \times 7$ grid.

The only practical method for solving the simultaneous equations resulting from the finite difference method was that which used high speed digital computers. The sets of sixteen and forty-nine equations were solved by the GaussSeidel method on the Navy's Logistics Computer at George Washington University, Washington, D. C. The remaining sets of equations were solved by International Business Machines Corporation, New York, New York, on the Type 650 Drum Calculator. The solutions of all sets

of equations are listed in tables I to VI. These values are theoretical deflections at the various node points on the plate under action of a triangularly distributed load corresponding to a maximum load ordinate of $\mathrm{p}_{\mathrm{f}}=2.8498 \mathrm{psi}$ at the fixed-fixed corner, except for the $2 \times 2$ grid for which $\mathrm{p}_{\mathrm{f}}=16.678 \mathrm{psi}$.


Coefficient patterns for moment at typical points in the plate, similar to those for deflections, are presented in figure 11.

To compute stress from these moment expressions, multiply by the constant $6 / h^{2}$ (reciprocal of section modulus of a rectangular section one inch wide).



Fig. 11. Finite difference equation patterns for moment ( $\mu=0.3$ ).

The experimental investigation was designed to be consistent with the Iowa Highway Commission assumptions of fixation and loads. The investigation was performed on thin trapezoidal aluminum plates 45 in. x 51 in., fixed at two edges and free on the other two. In plan these plates were geometrically similar to the wingwall shown in figure 1. A distributed load varying linearly from zero at the sloping edge to a maximum at the fixed corner was used. Strains and deflections at various points on the plate were measured. Figure 12 shows the test setup.

The actual loading was a distributed load simulated by a large number of free-standing concentrated loads, each of which was a combination of small modular weights. The weight sizes were $10 \mathrm{lb}, 5 \mathrm{lb}, 2 \mathrm{lb}, 0.67 \mathrm{lb}$, and 0.33 lb . The 10 lb and 5 lb units were accomplished by inserting steel shot in one quart cans. The smaller weights were sand-filled plastic bags. By using these modular weights, it was possible to load the plate in six equal increments. The maximum total load was approximately $4,000 \mathrm{lb}$. It was not feasible to use more than $4,000 \mathrm{lb}$ because of the nature of the loading system and the material used.

Readings at various points on the plate at each increment of load deflection were taken by Federal full jeweled dial indicators with a least count of 0.001 in . and a range of 1 in . Simultaneously, SR-4 resistance type strain gage readings were taken for a number of points. Linear type gages were used at points where directions of principal stresses were assumed to be known, and rosette type gages were used at other points.

The first set of tests was performed on a $3 / 4$ in. plate of size and shape previously mentioned. It was found that the deflections and strains even under the maximum load of 4000 lb were too small and erratic to be reliable. To obtain greater deflections and strains under the maximum load of $4,000 \mathrm{lb}, 1 / 2 \mathrm{in}$. and $5 / 8 \mathrm{in}$. thickness


Fig. 13. Plate before loading.
 plates of the same overall size ( $45 \mathrm{in} . \mathrm{x} 51 \mathrm{in}$.) were obtained.
The $3 / 8$ in. plate was tested first. The purpose of the test was one of reconnaissance, therefore only a minimum number of gages were used. Load-deflection and load-strain curves for various points on the plate were not linear, and the plate did not return to consistent zero positions even after a series of loading cycles. Nonlinear slippage of the supports was suspected, and an attempt was made to correct this by inserting cement grout between the plate and its channel supports. This grouting procedure solved the problem of support slippage in that the plate consistently returned to its original position after being unloaded, usually within the least count of the deflection dials ( 0.001 in .). On the basis of this performance, it was decided to gage the plate completely and perform final tests. Approximately 80 SR-4 resistance type strain gages were then applied, and final tests of the plate were commenced using the system of six load increments.


Fig. 14. Plate under maximum load.

Load-deflection curves for the dial gages and load-strain curves for the strain gages were straight lines though the lower load range, but after a loading equivalent to $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$ they lost their linearity, due to membrane action of the plate. It was evident that to obtain sufficient and reliable data in the straight-line range of these curves, smaller increments of load with a maximum of 1000 lb must be used. On examination of the loading procedure and the inhercat errors in experimental observations, it was concluded that a further refinement of load increments was not justifiable due to the very small deflections and strains that were involved.

Because of the performance of the $3 / 8$ in. plate the decision was made to test the $1 / 2 \mathrm{in}$. plate in an attempt to obtain more reliable observations and results in the linear range of structural behavior. Photographs of this $1 / 2 \mathrm{in}$. plate in place and during test are shown in figures 13 and 14 . On the basis of observations on the $3 / 8 \mathrm{in}$. plate, more complete gaging was accomplished in certain areas where previous data were weak. This more complete gaging resulted in a total of 25 dial gages and 118 SR-4 strain gages, the locations of which may be seen in figures 15 and 16.
Three complete tests were performed on the $1 / 2 \mathrm{in}$. plate, each test involving six equal increments of load up to approximately 4000 lb total weight. The load was removed and final readings with zero load on the plate were taken immediately after the maximum load was applied in each of the three tests. The majority of the deflection dial readings before and after test agreed within the least count of the dial ( 0.001 in .) ; the maximum deviation observed at the outside corner, was 0.004 in . out of a maximum deflection of 0.668 in .

Load-deflection curves for each dial indicator and load-strain curves for each strain gage

were then drawn for each of the three tests. It was found that the load deflection curves for each test were almost identical, but loadstrain curves did not agree as closely, due to the exceedingly small strains involved (in many cases less than the least count of the M-unit). It was therefore decided that the best overall strain gage results could be obtained by averaging the data from the three tests. Sample loaddeflection and load Ee (modulus of elasticity times unit strain) curves are shown in figures 17 and 18. The linearity of both sets of curves throughout the loading sequence is evident. The slopes of these curves are respectively deflection and Ee for a load corresponding to $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$ at the fixed corner. The resultant slopes of all experimental curves are in table VII. The notation used is shown in figures 15 and 16.

As a further check on the consistency of the experimental observations, figures 19 to 22 show deflection sections and Ee sections for each corresponding grid line on the plate. In drawing these curves, the slopes previously evaluated were used as ordinates. With the deflection and Ee sections established, it was possible to construct deflection and Ee contour diagrams or charts for the $1 / 2 \mathrm{in}$. plate subjected to a triangular loading equivalent to $\mathrm{p}_{\mathrm{f}}=1$ psi. The uniformity of these contour charts, reductions or



Fig. 16. Location of SR-4 gages.


Fig. 17. Load-deflection curves (41-5 to 45-5).


Fig. 19. Deflection sections parallel to $x$-axis.


Fig. 21. Ee sections parallel to $x$-axis.


Fig. 18. Load Ee curves ( $\mathrm{Al}-\mathrm{Y}$ to $\mathrm{K} 1-\mathrm{Y}$ ).


Fig. 20. Deflection sections parallel to $y$-axis.


Fig. 22. Ee sections parallel to $y$-axis.


Fig. 23. Deflection contours for $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$.


Fig. 25. Ee $e_{y}$ contours for $p_{f}=1$ psi.
miniatures of which are shown in figures 23 to 26 , give another check on the consistency of ex-


Fig. 24. $\mathrm{Ee}_{\mathrm{x}}$ contours for $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$.


Fig. 26. $E e_{n}$ contours for $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$.
perimental observations. All values for comparison of results of experimental with theoretical were taken from the original large scale charts.

## COMPARISON OF THEORETICAL AND EXPERIMENTAL RESULTS

Comparisons of theoretical and experimental deflections are listed in tables VIII to XIII. It may be observed that the solutions resulting from the use of thirty-six and forty-nine equations agree very favorably with those obtained from the experimental investigation. Convergence graphs, which are plots of deflections versus the grid spacing used in their difference equations, are included in figures 27 and 28 . These graphs are for deflections at the center point of the plate and the free corner respectively. The experimentally observed value is the superimposed horizontal line. In all cases, values obtained from a grid spacing of 7.5 in . (36 nodes) compare very favorably with those
obtained experimentally. As the grid spacing approaches zero and the number of nodes approaches infinity, the results should approach a constant value. This value should be equal to the value that would be obtained from a rigorous mathematical solution of Lagrange's equation. Because of this, the curves were extrapolated graphically, and the probable theoretical values for deflection of the respective points when $\lambda=0$ are represented by the intersections of the curves with the $y$-axis.

Inasmuch as the equations for predicting stresses in terms of deflections are linear in these deflections, it may be assumed that accurate predictions of deflections will result in


Fig. 27. Convergence graph for deflection at center of $1 / 2$ in. plate for $p_{f}=1 \mathrm{psi}$.


Fig. 29. Convergence graph for stress at L1-Y.


Fig. 28. Convergence graph for deflection at free corner for $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$.

| Deflection (in.) |  |  |  |
| :---: | :---: | :---: | :---: |
|  | Theoretical | Experimental | Percent ${ }^{\text {a }}$ |
| Node | $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$ | $\mathrm{p}_{\mathrm{f}}=1 \mathrm{psi}$ | difference |
| 11 | 0.01035 | 0.009 | 13.0 |
| 12 | 0.02220 | 0.019 | 17.0 |
| 13 | 0.03144 | 0.028 | 12.5 |
| 14 | 0.03881 | 0.035 | 11.0 |
| 15 | 0.04566 | 0.040 | 14.0 |
| 21 | 0.02055 | 0.018 | 14.0 |
| 22 | 0.04828 | 0.045 | 7.5 |
| 23 | 0.07258 | 0.069 | 5.0 |
| 24 | 0.09279 | 0.087 | 6.5 |
| 25 | 0.11214 | 0.105 | 7.0 |
| 31 | 0.02620 | 0.025 | 5.0 |
| 32 | 0.06609 | 0.062 | 6.8 |
| 33 | 0.10404 | 0.100 | 4.0 |
| 34 | 0. 13687 | 0.132 | 3.0 |
| 35 | 0.16783 | 0.160 | 4.0 |
| 41 | 0.02862 | 9.028 | 2.0 |
| 42 | 0.07647 | 0.072 | 6.0 |
| 43 | 0.12490 | 0.120 | 4.0 |
| 44 | 0.16782 | 0.165 | 4.8 |
| 45 | 0.20712 | 0.202 | 2.5 |
| 51 | 0.02956 | 0.025 | 18.0 |
| 52 | 0.08417 | 0.073 | 15.0 |
| 53 | 0.14170 | 0.144 | -2.2 |
| 54 | 0.19272 | 0.188 | 2.5 |
| 55 | 0.23716 | 0.228 | 4.0 |


| Table XII. | Deflection comparisons | for $6 \times 6$ grid. |  |
| :---: | :---: | :---: | :---: |
|  | Deflection (in.) |  |  |$]$

accurate predictions of stress. This is found to be true of deflections are carried to at least five places. A convergence graph for stress at Lly, which is similar to those drawn for deflections, is included in figure 29. This curve was also extrapolated graphically so that the probable theoretical value for stress at Lly when $\lambda=0$ is represented by the intersection of the curve with the $y$-axis. The results of this convergence graph in addition to those for deflection are presented in table XIV.
This investigation has been restricted to observing and predicting the structural behavior of a $1 / 2 \mathrm{in}$. aluminum plate of size shown in figure 12, when subjected to a normal distributed load varying linearly from the sloping edge. If it is assumed that reinforced concrete is homogeneous and of constant moment of inertia ${ }^{19, \text { p. } 422 \text {, these }}$ results through the principles of

| Table XIII. Deflection comparisons for $7 \times 7$ grid. |  |  |  |
| :---: | :---: | :---: | :---: |
|  | Deflection (in.) |  |  |$]$

${ }^{\text {a Based on experimental. }}$
similitude ${ }^{9}$, may be used to predict the structural behavior of a reinforced concrete wingwall of geometrically similar shape when subjected to a similar type loading. The application of these principles of similitude is not included in this bulletin but will be indicated in bulletin no. 183.

## DISCUSSION

Many items may influence the results of the experimental and theoretical investigations. A few of the more important follow:

1. Simplification of sloping edge. Since loading approached zero at this edge, it was decided this simplification would be just-

Table XIV. Results of convergence graphs.

| Nodes | Deflection, free-corner (in.) | Deflection, center (in.) | Stress <br> Lly (psi) |
| :---: | :---: | :---: | :---: |
| 4 | 0.253 | 0.111 | -.-- |
| 9 | 0.255 | ----- |  |
| 16 | 0.245 | 0.081 | 3170 |
| 25 | 0.237 | 0.075 | 3280 |
| 36 | 0.235 | 0.072 | 3340 |
| 49 | 0.233 | 0.070 | 3360 |
| Experimental | 0. 228 | 0.069 | 3300 |
| Theoretical | 0.228 | 0.066 | 3450 |

ified. Ignoring other possible compensating errors the close agreement between the analytical and experimental results would indicate that this simplification is valid.
2. Round off errors in coefficients and remainders. In writing the finite-difference equations, coefficients and remainders were carried to as many places as convenient on an electric calculator.
3. Shear deflection. The theoretical method as used in this investigation ignores the effect of shear deflection. This omission would tend to make theoretical deflections smaller than experimental.
4. Size of grid spacing. Certainly the size of grid spacing used in the finite-difference method affects theoretical results. The convergence graphs, figures 27 to 29 , indicate this effect.
5. Fixation of edges. Absolute fixation could not feasibly be reached in the model. Plots of observed strains down each fixed edge indicated slight yielding or rotation of the supports. Such rotation was reduced by stiffening the support channels on the loading frame. True fixation in the theoretical analysis tends to make theoretical deflections smaller than experimental.
6. Membrane forces. The linearity of load-deflection and load-Ee curves indicate that membrane forces for the $1 / 2 \mathrm{in}$. plate were small. Membrane forces are neglected in the theoretical analysis.
7. Plate thickness. Measurements of thickness taken at various points indicated a variation
of only 0.005 in . in 0.500 in . The plate was, therefore, considered to be of constant thickness.
8. Homogeneity of plate. Tensile tests of samples taken at right angles to each other indicated similar physical properties as assumed.
9. Simulation of distributed load. A sufficient number of individual concentrated loads was used to approximate the distributed load of the theoretical analysis.
10. Compensating gages. Unstressed specimens to which the SR-4 compensating gages were applied, because of their size, were more sensitive to rapid changes in air temperature than the aluminum plate. Lack of consistent zero readings on the SR- 4 gages before and after test tended to confirm this. The SR-4 gages should have their temperature compensating gages on the opposite side of the plate. This would double the strain impulse, eliminate measurement of membrane strains, and better compensate for temperature. This improvement was used in later stages of the project.

## SUMMARY

Authorization was given by the Iowa Highway Research Board to the Iowa Engineering Experiment Station to conduct a research program on the structural behavior of reinforced concrete bridge abutment wingwalls of the types built by the commission. This bulletin reports on stages one and two of a four stage project. Stages one and two have been conducted as follows:

1. An exhaustive review of literature was performed to determine if such a study had previously been made. No record of research of this type was discovered.
2. A questionnaire was distributed to several hundred highway, railway, and consulting engineers throughout the United States and Canada.
3. The result of the literature review and questionnaire survey which together were stage one of the project was that a thorough study of the subject was needed.
4. The method of finite differences was used to solve the Lagrange plate equation written for a plate of the wingwall type.
5. Solutions were obtained corresponding to six different grid spacings.
6. The various solutions were compared with experimental results obtained by testing a $1 / 2 \mathrm{in}$. aluminum plate which was considered a model of a typical wingwall.
7. This comparison indicated that satisfactory predictions of structural behavior may be made from the set of equation corresponding to the $6 \times 6$ grid ( 36 simultaneous equations).
8. Stage three will use these findings to present moment contours for constant thickness bridge abutment wingwalls of the various proportions being used by the Iowa State Highway Commission. This stage will be reported in bulletin 183.
9. Stage four will provide an analytical procedure for the structural analysis of variable thickness wingwalls. A typical variable thickness wingwall will be analyzed for moments. This stage will be reported in bulletin 184.

## CONCLUSIONS

1. A rigorous mathematical solution of the governing differential equations for many engineering structures by structural engineers is not practical or convenient because of the mathematical complexity of such a solution as compared with numerical methods which give adequate results.
2. The finite-difference method for the approximate solution of differential equations of the types commonly found in engineering phenomena is the simplest and most direct of the numerical methods investigated.
3. With the advent of the high speed digital computer, simultaneous linear algebraic equations resulting from the application of the finitedifference method may be economically solved.
4. The finite-difference method for prediction of plate behavior gives reasonable results for a plate of the type, restraints, and loading used in this investigation when a 36 node grid system is used. This conclusion was found to agree with that of previous investigators 4, p. 20.

> Using an analogous grid consisting of six north-south beams and six east-west beams and solving directly linear equations containing all three unknowns at each joint, . . . the computed center moment on a uniformly loaded square plate agrees remarkably well with Henri Marcus' solution by the theory of elasticity.
5. Many engineering problems may be solved through application of the finite-difference method coupled with high-speed digital comuters. A few of the more important of these types of problems have been outlined, 10 .
6. The load system used very closely approximated that of a theoretically distributed load.

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## APPENDIX

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A research project on the structural behavior of wing walls of bridge abutments is being conducted by the Iowa Engineering Experiment Station under the sponsorship of the Iowa Highway Research Board. The purpose of this project is to study the structural behavior of typical reinforced concrete wing walls.

A search of the available literature on wing walls of bridge abutments has been conducted. Few of the references discovered gave any idea of the method of designing such walls. The suggestion most commonly made was to design the wall as a simple cantilever retaining wall and then either eliminate the connection to the breastwall by means of a construction joint, or simply ignore it and let the wall crack. We believe we can be of service to all engineers engaged in the design of such structures if we can assemble the information which may be available in organizations such as yours.

We are sending this letter and attached questionnaire to the various highway commissions, railroads, and consulting firms in the United States and Canada who might have occasion to design such structures. If you do not wish to answer this questionnaire personally, please have the person in your organization who is best qualified to do so.

Though you and your organization are very busy, we feel justified in asking you to take a little of your time to provide us with the information requested. We hope that the response to this request will provide us with material of such value that it can be published so that it will become available to the profession.

We shall appreciate any information you can supply us. If you would like to have it, we shall be glad to send you a copy of the report on this survey when it is completed.


## Publications of the lowa Engineering Experiment Station

The Iowa Engineering Experiment Station publishes reports of the results of completed projects in the form of technical bulletins. Other research results are published in the form of Engineering Reports.

Single copies of publications not out of print may be obtained free of charge, except as noted, upon request to the Director, Iowa Engineering Experiment Station, Ames, Iowa. The publications are available in many libraries. *Indicates out of print.

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